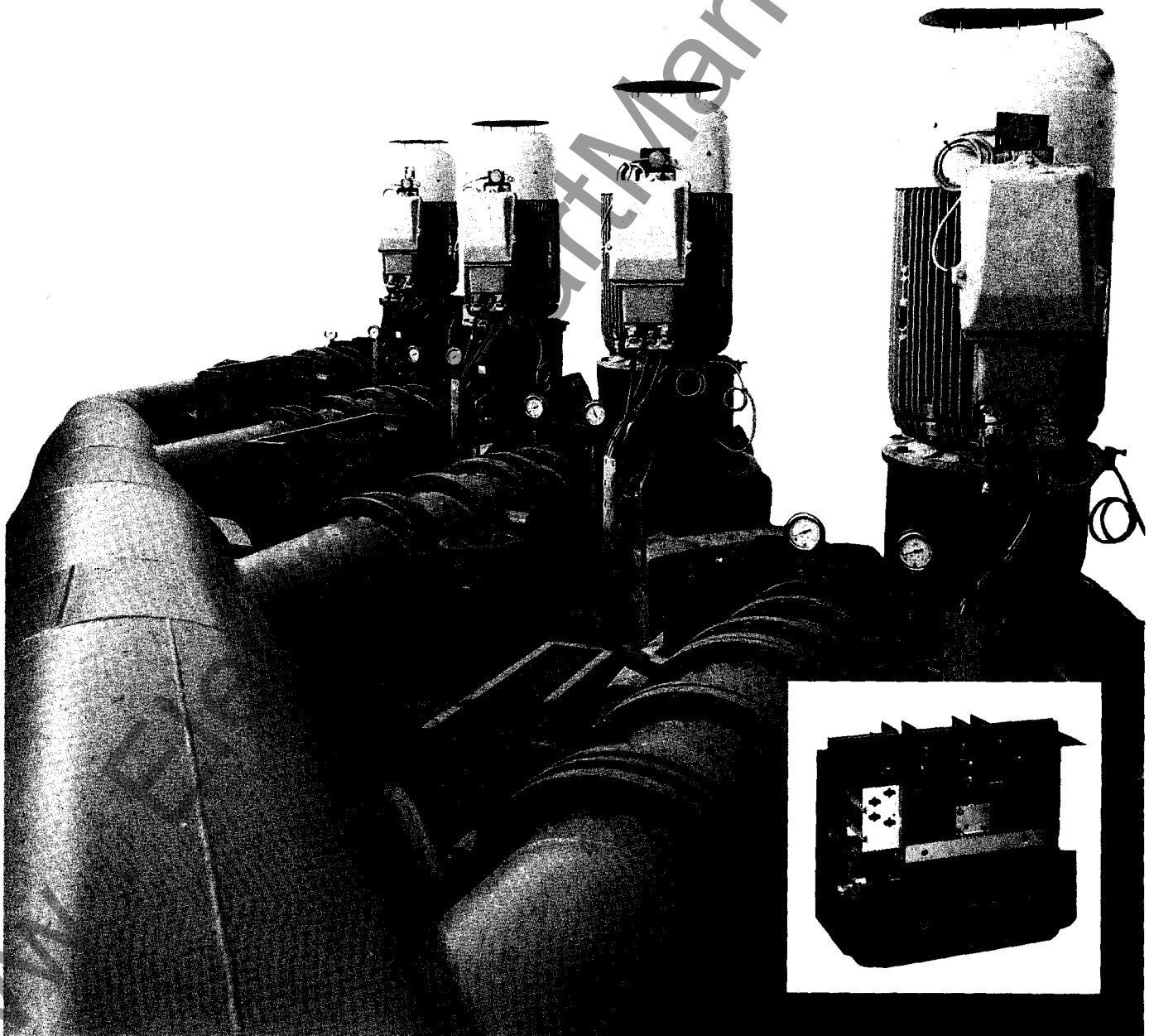


MERLIN GERIN

**Rollarc
R400-R400D
up to 12 kV**



mastering electrical power



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description

field of application

utilisation range

description

The **Rollarc** three-pole indoor contactor uses sulphur hexafluoride (SF₆) gas for insulation and circuit-breaking.

Circuit-breaking is based on the rotating arc principle. The basic version is made up of three pole units installed in the same insulating enclosure. The part of the enclosure containing the active parts of the poles is filled with SF₆ gas at a gauge pressure of 2.5 bars. There are two types of Rollarc contactors:

- the R400 with magnetic holding
- the R400D with mechanical latching.

main advantages

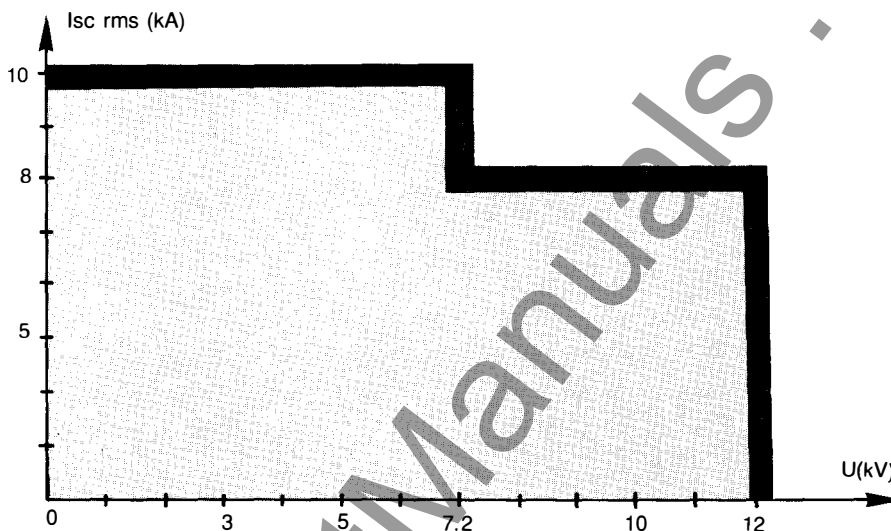
- a modern and tested circuit-breaking technique featuring SF₆ safety,
- no maintenance for active parts,
- high mechanical and electrical endurance
- low switching surges without additional devices (surge arrester)
- insensitivity to the environment
- gas pressure may be continuously monitored.

field of application

protection and control of:

- MV motors
- capacitor banks and power transformers

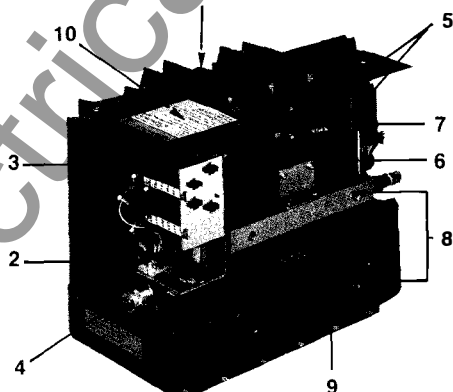
utilisation range



Standards

Rollarc complies with the following standards and specifications:

- IEC publication 470
- IEC 420
- BS 775 part 2
- NEMA ICS 2-324
- VDE 0660 part 103-8-84



- 1 : MV connections
- 2 : LV connections
- 3 : auxiliary contacts
- 4 : pressure switch (optional)
- 5 : electromagnetic operating mechanism
- 6 : mechanical latching device (R400D)
- 7 : opening release
- 8 : fixation points
- 9 : insulating enclosure
- 10 : rating plate

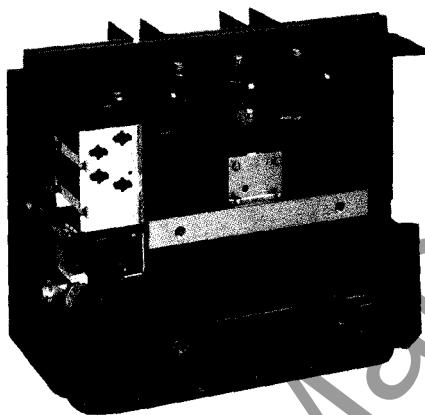
Installation references: SOLMER, MICHELIN, SHELL, ESSO, CFR, PECHINEY, NAPHTACHIMIE, USINOR, SACILOR, SOLLAC. NUCLEAR AND CONVENTIONAL THERMAL POWER STATIONS. MINES DE SAAR (WEST GERMANY) NOKIA (FINLAND) KAFK (SWEDEN).

installation type

The Rollarc R400 and R400D contactors are available in three versions:

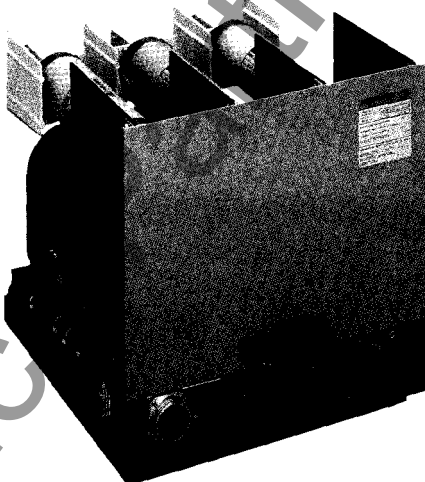
Basic version:

Contactors alone, without the cradle.



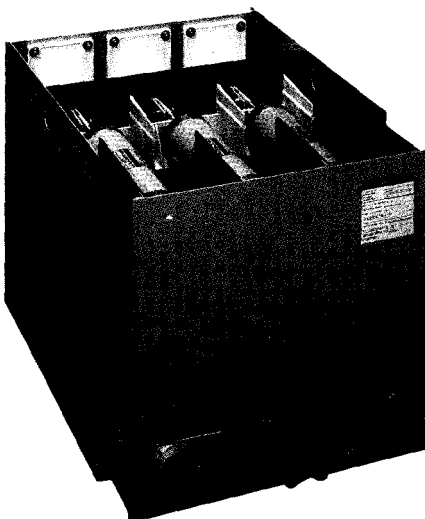
Fixed version:

The contactor with the control auxiliaries is mounted on a fixed cradle.



Withdrawable version:

The contactor with the control auxiliaries is mounted on a withdrawable cradle.



Fixed and withdrawable versions may be equipped with fuses when the short-circuit current is greater than the contactor rating. The fuses used are of the indoor Fusarc type (1) with strikers that actuate the contactor opening mechanism.

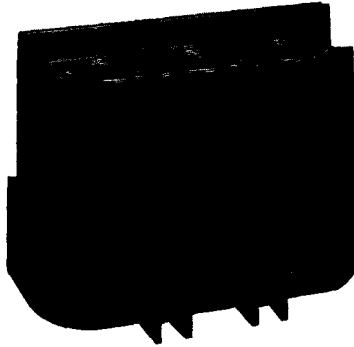
description of basic version

Enclosure

The epoxy resin enclosure ensures:

- high mechanical strength enabling use as a support for the active parts and resistance to electromechanical stress
- excellent dielectric strength due to the nature of the material and the design
- a very reliable seal (sealed pressure system in compliance with standard IEC 56, 1987 edition, appendix EE).

The filling pressure remains constant throughout the life of the contactor.



Active parts and operating mechanism

The essential parts include the:

- arc interruption device
- insulating rod which actuates the mobile contacts and the corresponding fixed terminal.

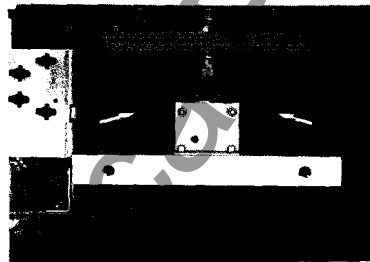
These parts are housed in an enclosure which is sealed for life and are thus totally insensitive to the environment. The resulting elimination of corrosion increases the reliability of the device.



Electromagnetic coils

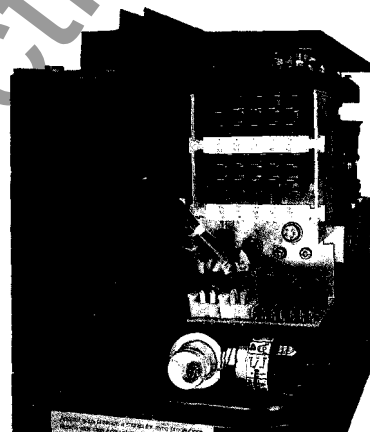
Rollarc is actuated by electromagnetic coils that ensure closing and hold the device in the closed position.

↗ coil



Auxiliary contacts

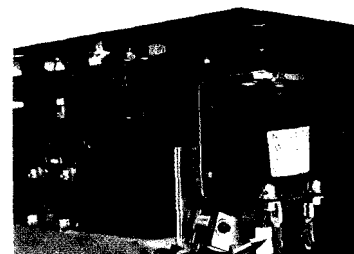
The auxiliary switch subassemblies are always mounted on the enclosure.



Mechanical latching

The R400D is actuated by electromagnetic coils that ensure closing of the device and has a mechanical latching device which holds the contactor in the closed position without a continuous power supply. A release is used to free the latching mechanism.

↗ Mechanical latching device



electrical characteristics

electrical characteristics

rated voltage Ua kV (50-60 Hz)	rated insulation level impulse(1) 1mn kV peak 50-60 Hz kV rms		breaking capacity at U (kV) kA with fuses (2) (kA)		rated current A	making capacity (kA) peak	with fuse (prospective current) (kA)	3 sec. short time current kA rms	electrical and mechanical endurance at the load current
3.3 to 4.76	60	20	10	50	400	25	125	10	300 000 operations (magnetic holding) 30 000 operations (mechanical latching)
7.2	60	20	10	50	400	25	125	10	
12	60	20	8	40	400	20	100	8	

opening time at U :

breaking time

closing time

without relays: 20 to 35 ms
with relays: 25 to 45 ms

without relays: 30 to 55 ms
with relays: 35 to 55 ms

without relays: 80 to 160 ms
with relays: 85 to 170 ms

- (1) optional: 75 kV impulse/28 kV rms on basic version only
(2) Fusarc fuses see sheet AC25E (fuses 3-36 kV)
(3) 400A continuous (no overload possible)

Control circuit

rated supply voltage (Un)..... DC: 48, 60, 110, 125, 220 V
AC: 110, 127, 220 V (1)

power consumption

- pick-up..... DC: 1050 W
AC: 900 VA
- seal-in..... DC: 30 W
AC: 40 VA
- opening..... DC: 80 W
AC: 100 VA

(1) for other values, consult Merlin Gerin

Auxiliary switches

- rated current..... 10 A
- breaking capacity..... DC: (L/R = 0.015 s) 0.5 A / 220 V
AC: (p.f. = 0.3) 10 A / 220 V

maximum switching capacities

When the contactor is used in conjunction with fuses, the maximum switching capacities may be determined using the fuse curves and by taking into account:

- the characteristics of the load (motor starting currents, starting times, transformer inrush currents).

- the amplitude of the limited interrupted current which is a function of the prospective fault current and the fuses employed. The limited interrupted current should not exceed the electrodynamic withstand capacity of the contactor.

For values less than those presented in the table below, see:

page 21 for motor control, technical sheet AC25E for transformers

service voltage kV	without fuse			with fuses				transfo. (standard max rating) kVA	Capacitors (single bank) Kvar	
	motors (1) kW	transfo. kVA	capacitor banks kVAR	max. fuse rating see doc. AC25E (I=292 mm) (2)	motors kW (1)		10 sec. start Is/In = 6			
					5 sec. start Is/In = 6	10 sec. start Is/In = 6	10 sec. start Is/In = 6	10 sec. start Is/In = 6		
					starts/h : 6	starts/h : 12	starts/h : 6	starts/h : 12		
3.3	1560	1800	1255	250	1160	1060	1060	940	1000	790
3.6	1690	1965	1370	250	1260	1150	1150	1020	1250	865
4.16	1960	2270	1585	200	820	735	735	665	1000	800
6.6	3100	3600	2510	200	1295	1165	1165	1050	1600	1270
7.2	3380	3925	2740	200	1410	1270	1270	1145	1600	1385
10	4690	5455	3810	100	520	445	445	445	1250	960
12	5630	6545	4570	100	625	535	535	535	1600	1155

(1) with p.f. = 0.92 n = 0.94.

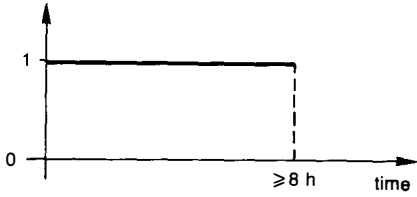
(2) for higher fuse ratings, consult Merlin Gerin.

*Note: Fuse ratings depend on the maximum power.

For lower powers, the correct fuse rating must be determined (see page 21).

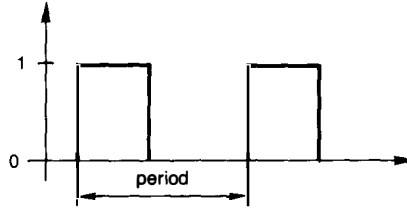
contactor operating conditions (without fuses)

IEC standard 470 (chapter 2) defines three types of contactor operation:



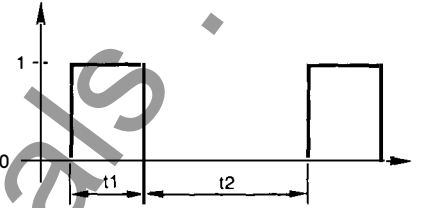
■ **continuous operation**

In position 1, the contactor equilibrium temperature is reached.



■ **periodical intermittent operation**

(or intermittent)
In position 1, the contactor equilibrium temperature is not reached.



■ **short-time operation**

In position 1, the contactor equilibrium temperature is not reached.
t1 : standardized values -
10 mn - 30 mn - 60 mn - 90 mn
t2: time required for the contactor to cool to the temperature of the cooling medium

Intermittent and short-time operation

Allowable overcurrents

The two sets of curves presented here can be used to determine allowable overcurrents in the Rollarc contactor:

- the maximum value of an overcurrent and the cooling time.

Using the permanent current value I_p , figure 1 can be used to determine the maximum duration of T_{oc} along line 1.

The time required for cooling T_c to ensure that the equilibrium temperature is not exceeded may be determined using figure 2.

Example: a Rollarc contactor with a permanent operating current $I_p = 240A$ can withstand a temporary overload of 2400A for 32 seconds. The cooling time T_c is:

- 25 minutes if the circuit is open.
- 28 minutes if a 120A current flows through the contactor.
- 48 minutes if a 200A current again flows through the contactor.

■ **Cyclical overcurrent**

the fourth parameter (see line 2 between figures 1 and 2) can be determined when three of the four below are known:

- I_{oc} overcurrent
- T_{oc} duration of overcurrent
- I_c cooling current
- T_c duration of cooling

Example :

I_{oc} 1200A for 10 seconds
 T_c 200A for 2 minutes

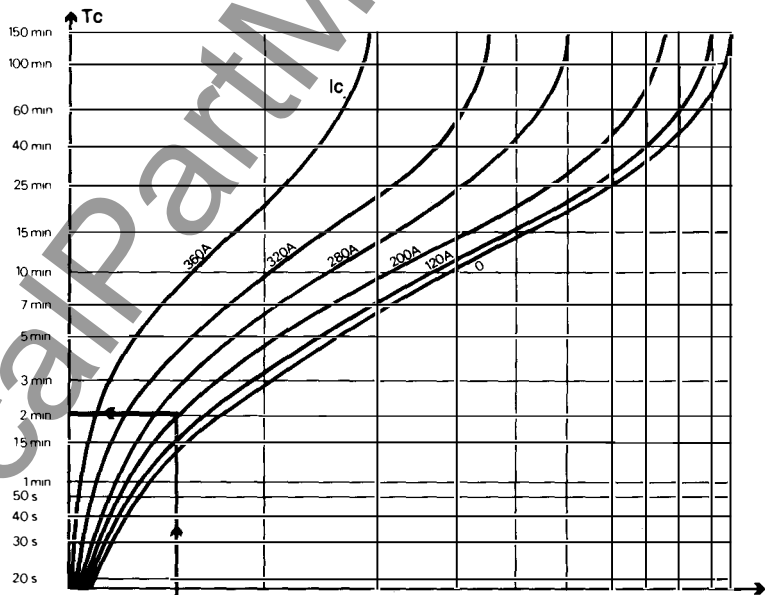
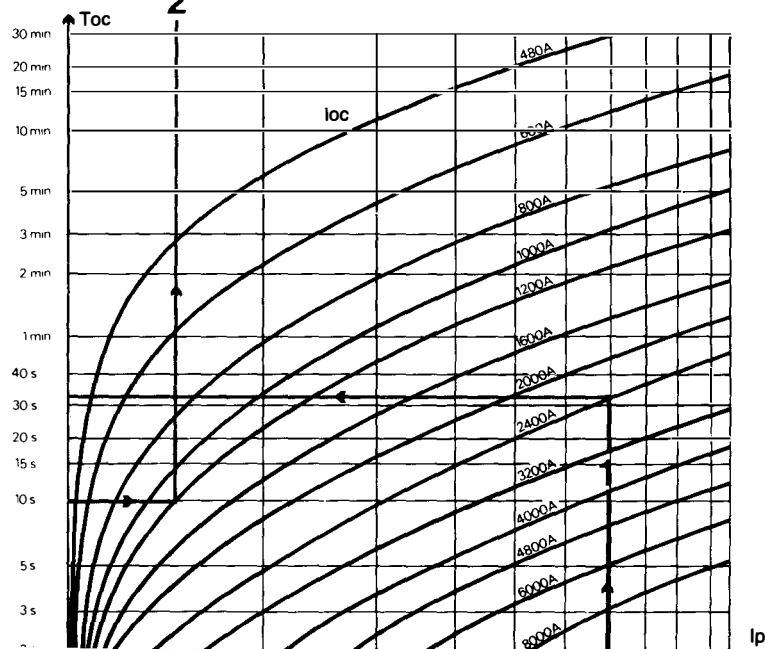


fig. 2



Ip

operating mechanism and equipment

Rollarc operating mechanism

The contactor is closed by an electromagnet (pick-up coil YF).

■ for the magnetically held contactor **R400**, two seal-in coils (YM) are inserted in the circuit at the end of closing. The contactor is tripped by the opening of the holding circuit.

■ for the mechanically latched contactor **R400D**, the contactor is held in closed position by the mechanical latching system. The contactor is tripped by a shunt trip which releases the latching device.

Auxiliary switches

Rollarc contactors are equipped with ten changeover common point auxiliary switches.

Consult the equipment selection table for information on the number of available switches.

The optional pressure switch for alarm indications closes a changeover switch if the gas pressure drops below 1.5 bars.

Contact breaking capacity:

■ A.C. (p.f. = 0.6) 2.2 A at 127V

■ D.C. 0.5A at 120V
0.4A at 220V

selection of accessories	code	R400 magnetically held contactor			R400D mechanically latched contactor		
		basic version AC/DC	fixed version AC/DC	withdrawable version AC/DC	basic version AC/DC	fixed version AC/DC	withdrawable version AC/DC
closing electromagnet	YF	■	■	■	■	■	■
holding electromagnet (seal-in)	YM	■	■	■			
shunt trip	YD				■	■	■
number of auxiliary switches available (1)	CA	9	9	9	8	8	8
pressure switch	P	□	□	□	□	□	□
anti-pumping relay	KN				▲	■	■
closing relay	KMF	▲	■	■	▲	■	■
opening relay	KMO	▲	■	■	▲	■	■
operations counter (1)	PC		□	□		□	□
interlocking auxiliary switch* interlock	SE		■	■		■	■
"service position" indication	SQ2		□	□		□	□
equipment for MV fuses (fixing and "fuse blown" contacts)			□	□		□	□
withdrawable fixed frame (2)						□	
75 kV kit		□			□		
mechanical interlock		□			□		

(1) The operations counter uses one auxiliary switch.

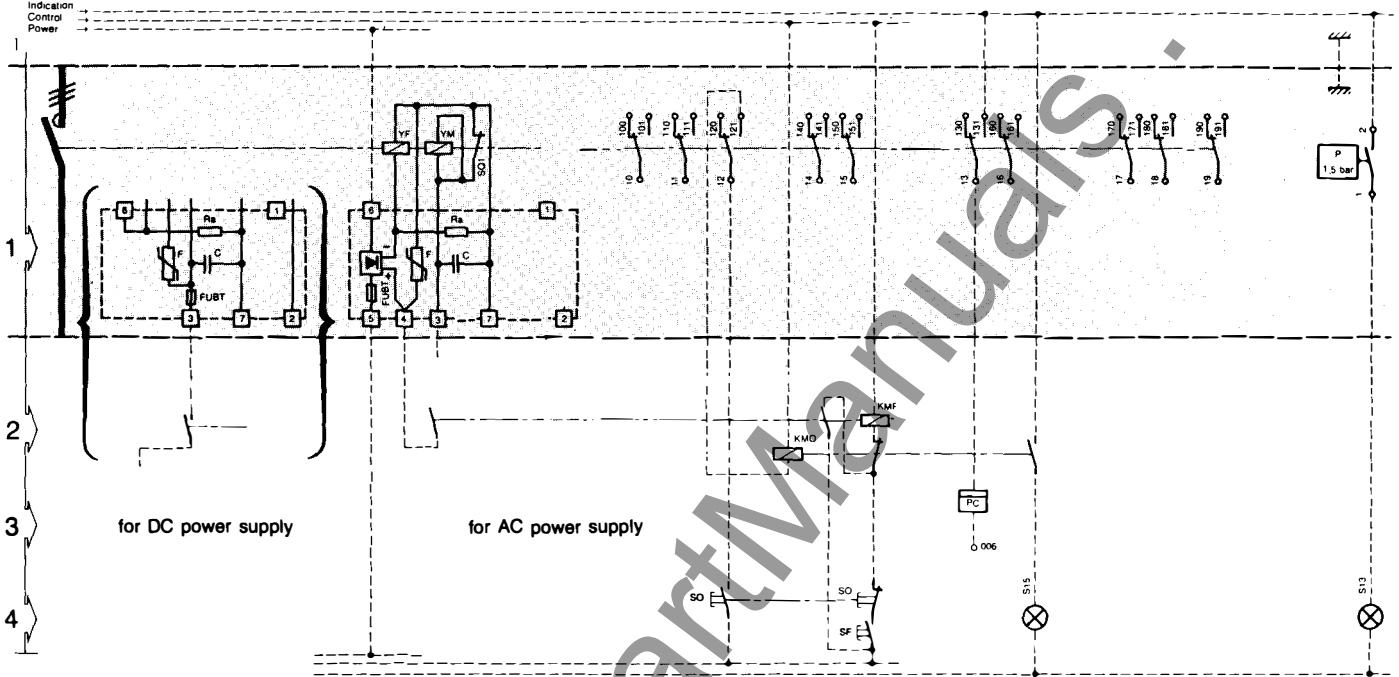
(2) Device may be padlocked on the fixed frame (1 or 2 padlocks).

*The interlock switch is actuated by the operating handle.

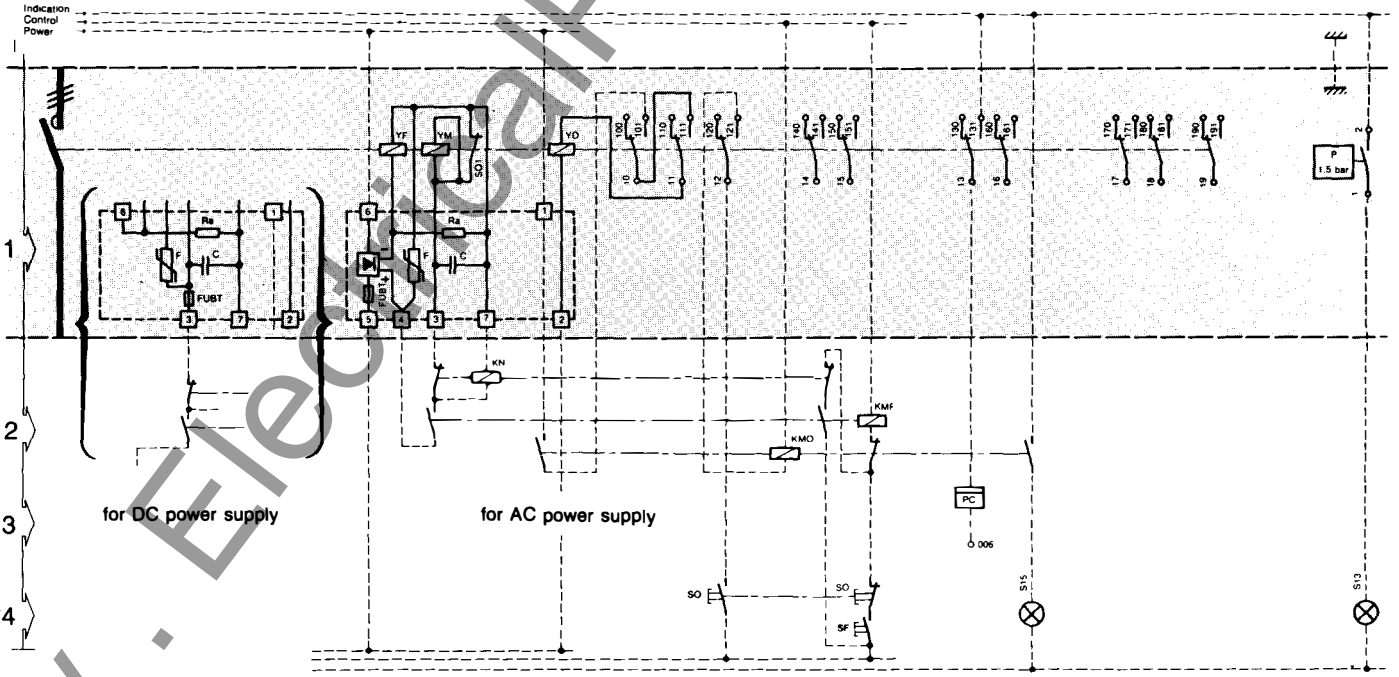
- standard equipment
- ▲ relay not supplied, wired by user (see diagrams).
- optional accessories

diagram

Rollarc 400 basic version



Rollarc 400D basic version



- 1: standard Merlin Gerin supply
- 2: control relay recommended by Merlin Gerin
- 3: options proposed by Merlin Gerin
- 4: O/C control unit (not supplied by Merlin Gerin)
- mechanical links
- Rollarc printed circuit alone
- connections supplied
- connections not supplied
- YF : closing coils
 ---: 1050 W ~ 900VA
 ---: 30 W ~ 40VA
- YM: seal-in coil
 ---: 80 W ~ 100VA
- YD: shunt trip
 ---: 80 W ~ 100VA
- SO1: limit switch. Seal-in coil contact
- C: capacitor C = 1uf x 2 U max = 250V

FUBT : low voltage fuse

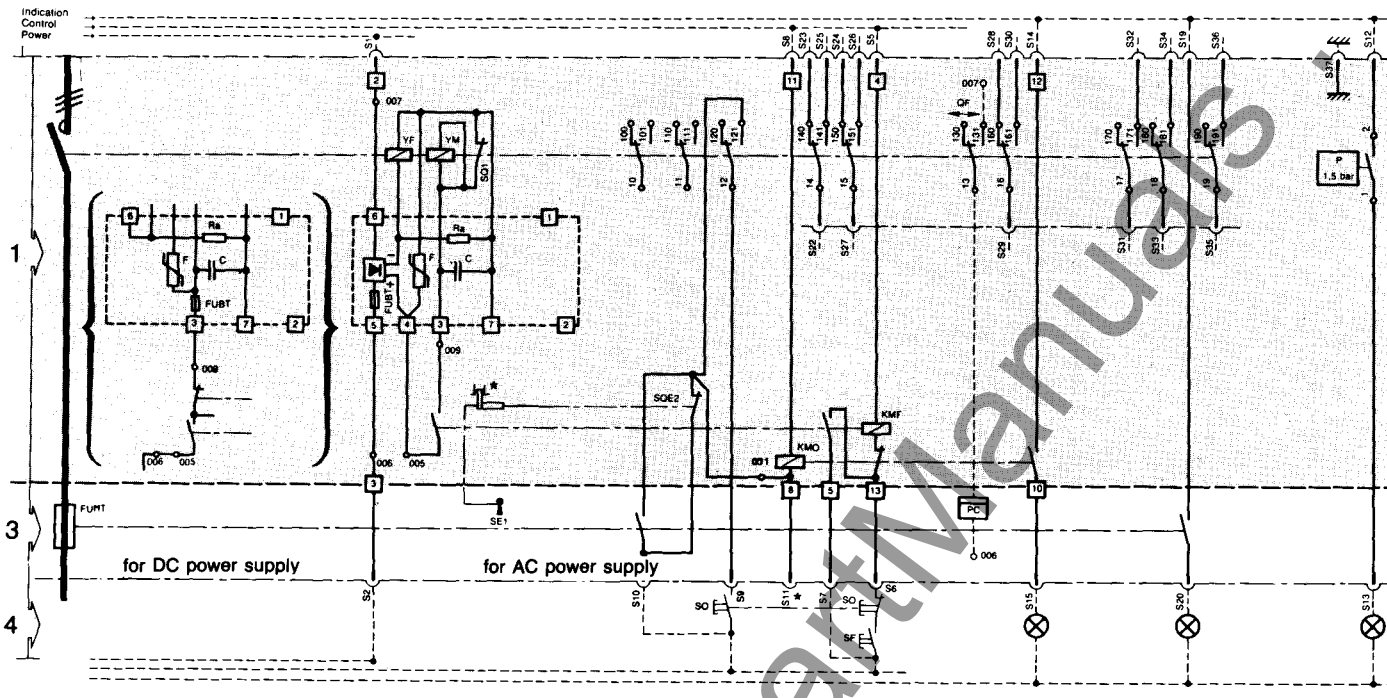
Un (V)	48	60-72	100-127	220-250
Ia (A)	10	3.15	2.5	1.25

QF: auxiliary switch I_a = 10A
 Breaking I_a (p.f. = 0.3) 10A/220V
 ~ 2.2A/220V --- (L/R = 0.15) 0.5A/220V
 P: pressure switch closing (S12-S13) P
 ~ 2.2A/220V --- 0.4A/220V
 SO: opening push button
 SF: closing push button
 PC: 6-digit operations counter

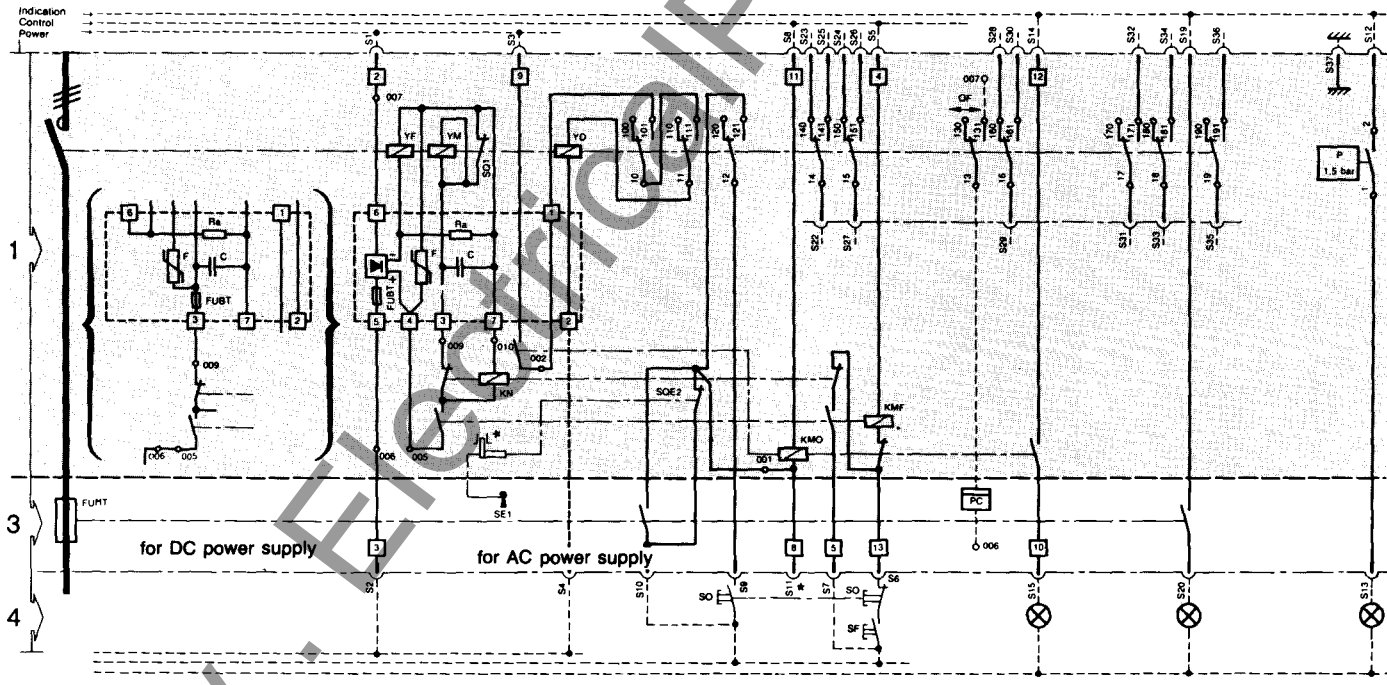
Un (V)	see table below		
	48	110	220
Ia (A) ~	10	10	10
p.f. = 0.4 (A)	1.1	0.4	0.24
L/R = 40 ms --- (A)	0.8	0.3	0.18
Coil consumption	--- 3 W	~ 4VA	

diagram

Rollarc 400 fixed version with electrical auxiliaries



Rollarc 400D fixed version with electrical auxiliaries



- 1: standard Merlin Gerin supply
- 3: options proposed by Merlin Gerin
- 4: O/C control unit (not supplied by Merlin Gerin)

--- mechanical links
 - - - Rollarc printed circuit alone
 - - - connections supplied
 - - - connections not supplied

*: mechanical locking. Contactor open
 Caution: do not connect S11 or 8 (emergency opening)

- FUPT: closing coils
- 1050 W ~ 900VA
- YM: seal-in coil
- 30 W ~ 40VA
- YD: shunt trip
- 80 W ~ 100VA

FUBT : low voltage fuse				
Un (V)	48	60-72	100-127	220-250
Ia (A)	10	3.15	2.5	1.25

QF: auxiliary switch Ia = 10A
 Breaking I ~ (p.f. = 0.3) 10A/220V
 ~ (L/R = 0.15) 0.5A/220V

P: pressure switch closing (S12-S13) P
 ~ 2.2A/220V ~ 0.4A/220V

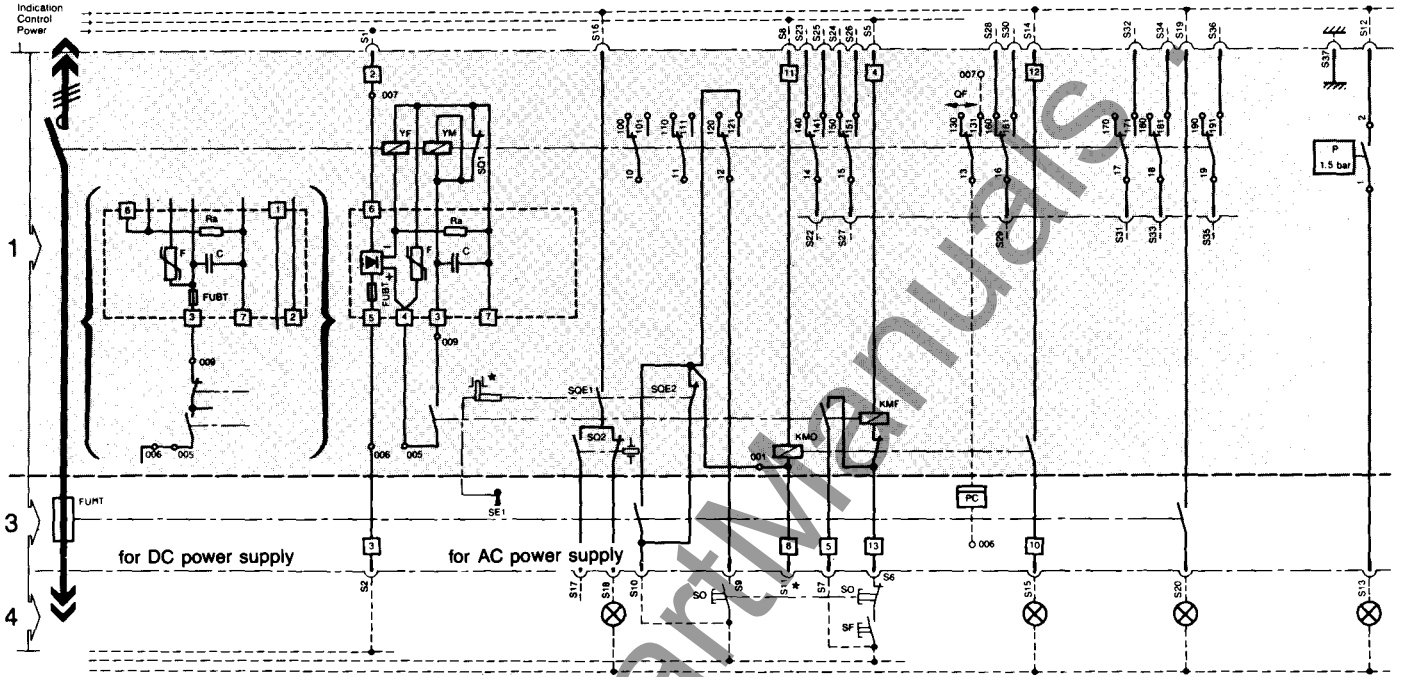
SOE1: open/contactor locked open mechanically
 SOE2: closed/contactor locked open mechanically
 opening command maintained

SO: opening push button
 SF: closing push button
 PC: 6-digit operations counter
 FUHT: HV fuse

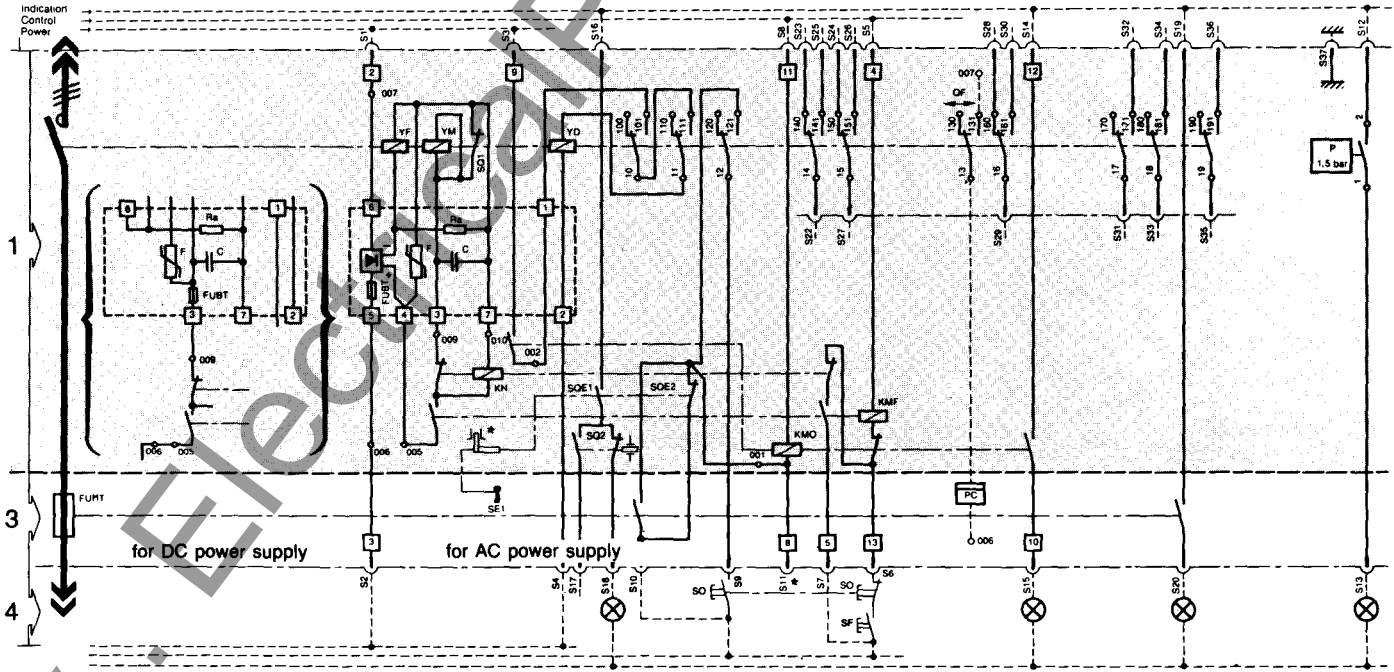
KN: end of closing relay
 KMF: closing relay
 KMO: opening relay

Un (V)	see table below		
	48	110	220
Ia (A) ~	10	10	10
p.f. = 0.4 ~ (A)	1.1	0.4	0.24
L/R = 40 ms ~ (A)	0.8	0.3	0.18
Coil consumption	~ 3 W	~ 4VA	

Rollarc 400 withdrawable version with electrical auxiliaries



Rollarc 400D withdrawable version with electrical auxiliaries



- 1: standard Merlin Gerin supply
- 3: options proposed by Merlin Gerin
- 4: O/C control unit (not supplied by Merlin Gerin)

— mechanical links
 - - - Rollarc printed circuit alone
 — connections supplied
 - - - connections not supplied

*: mechanical locking. Contactor open
 Caution: do not connect S11 or 8
 (emergency opening)

FU: closing coils
 ---: 1050 W ~ 900VA
 ---: 30 W ~ 40VA
 YF: closing coils
 ---: 80 W ~ 100VA

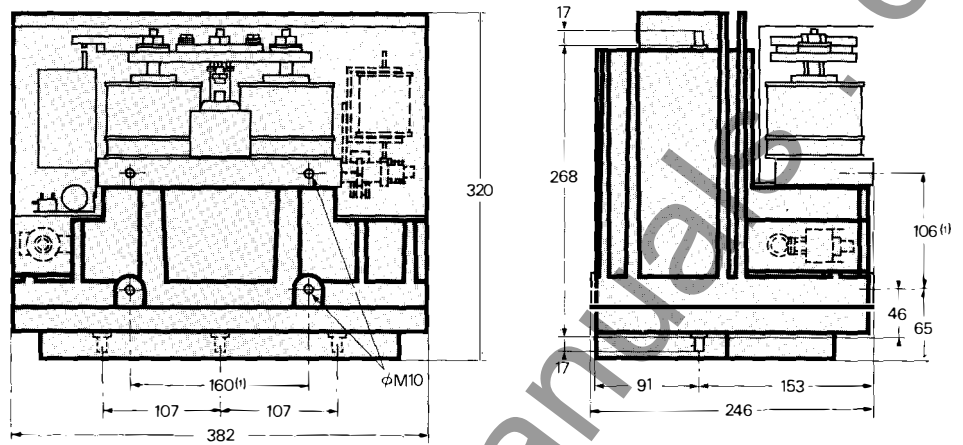
FUBT : low voltage fuse				
Un (V)	48	60-72	100-127	220-250
Ia (A)	10	3.15	2.5	1.25

QF : auxiliary switch I_a = 10A
 Breaking I_~ (p.f. = 0.3) 10A/220V
 --- (L/R = 0.15) 0.5A/220V
 P : pressure switch closing (S12-S13) P
 ~ 2.2A/220V --- 0.4A/220V
 SQE1: open/contactor locked open mechanically
 SQE2: closed/contactor locked open mechanically
 opening command maintained
 SO: opening push button
 SF: closing push button
 PC: 6-digit operations counter
 SQ2: service position indication

Un (V)	see table below		
	48	110	220
Ia (A) ≈	10	10	10
p.f. = 0.4 ~ (A)	1.1	0.4	0.24
L/R = 40 ms --- (A)	0.8	0.3	0.18
Coil consumption	--- 3 W	~ 4VA	

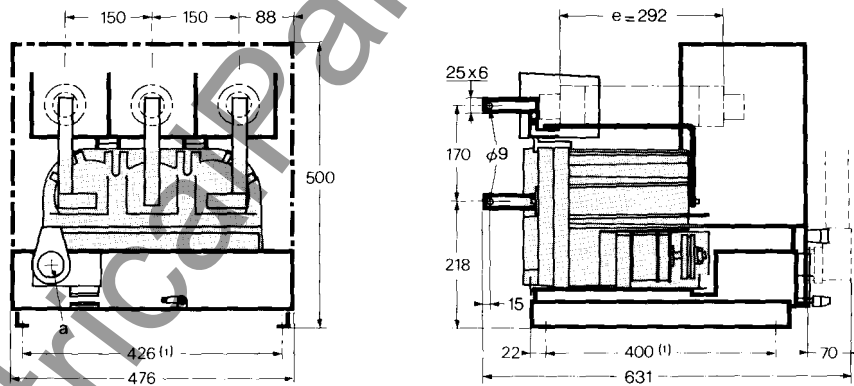
dimensions

basic version



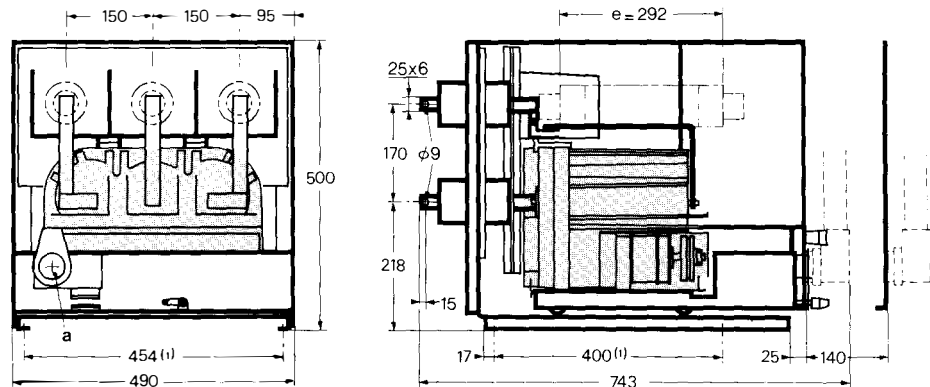
(1) mounting dimensions
approximate weight: 35 kg

fixed version



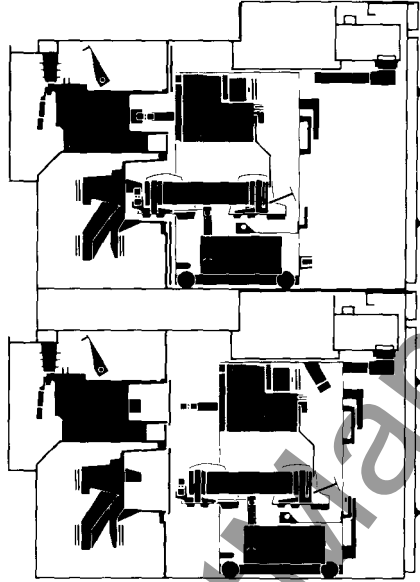
(a) LV connector
(1) mounting dimensions
approximate weight: 65 kg

withdrawable version

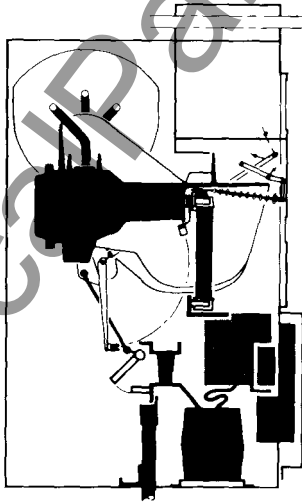


installation examples

**Withdrawable Fluair 100
factory-built cubicle**
(See technical sheet AC0099E)

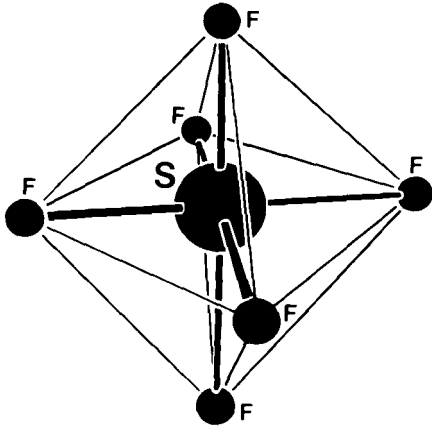


VM6 factory-built cubicle
(See technical sheet AC5E)



SF6 gas properties and Rollarc technique

Sulphur hexafluoride (SF6) gas properties



SF6 is a non-inflammable very stable, non-toxic gas, five times heavier than air. Its dielectric strength is much higher than that of air at atmospheric pressure.

gas for interruption

SF6 is "the" arc-interruption gas, combining the best properties:

- **high capacity for carrying away the heat** produced by the arc. The latter is rapidly cooled by convection during the arcing period.

- **high radial thermal conduction and high electron capturing capacity.**

When the current passes through zero, the arc is extinguished by the combination of two phenomena:

- SF6 permits rapid heat exchange from the center of the arc toward the exterior.
- fluorine atoms, which are highly electronegative, act as veritable "traps" for electrons.

Since it is electrons which are mainly responsible for electric conduction in the gas, the gap between the contacts recovers its initial dielectric strength through this electron capture phenomenon at zero current.

- **the decomposition of the SF6 molecule is reversible.**

The same mass of gas is therefore always available, making the device self-sustained throughout its operating life.

advantages of Rollarc

The Rollarc rotating arc contactor is a modern device with enhanced cooling of the arc by forced convection leading to the following advantages:

long life

This results from:

- high product reliability,
- very low wear of the active parts which require no maintenance,

- the excellent sealing of the enclosure, eliminating the need for subsequent filling.

mechanical endurance

The operating energy is reduced because arc rotation is directly created by the current to be interrupted.

The Rollarc contactor can withstand 300 000 operations without any parts being replaced.

electrical endurance

The long life of the Rollarc is due to the negligible degeneration of the gas and to low wear of the contacts.

The energy dissipated in the arc is low due to:

- the intrinsic properties of the gas,
- the short length of the arc,
- the very short arcing time.

Wear of the arcing contacts can be checked without opening the poles. The unit is capable of breaking all load and short-circuit currents, even in the case of frequent operation. With very high breaking capacity for a contactor, the Rollarc can be used in a fuse-contactor assembly capable of protecting any circuit against all types of faults including overloads.

low switching surges

The intrinsic properties of the gas and the soft break resulting from this technique means that switching surges are very low.

Concerning motor start-up, the unit is free from multiple prestrike and restrike phenomena which could damage the winding insulation.

operating safety

The Rollarc contactor operates at a low relative pressure of 2.5 bars.

continuous monitoring of the contactor pressure (optional)

A pressure switch actuates a contact in the event of an accidental drop in the pressure of the SF6 gas in the Rollarc unit.

insensitivity to external conditions

The Rollarc pole unit provides a totally gas-insulated system. It is a hermetically sealed enclosure filled with SF6 gas and housing the essential parts.

Rollarc is particularly suited to polluted environments such as mines, cement works, etc.

the rotating arc technique

the rotating arc principle

The exceptional characteristics of SF₆ gas are used to extinguish the electrical arc.

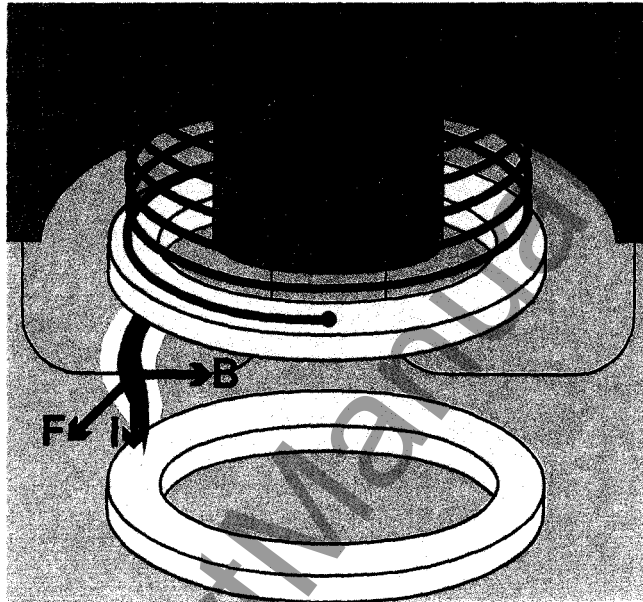
Cooling is enhanced by the relative movement between the arc and the gas.

In the rotating arc technique, the arc is set in motion between two circular arcing contacts (see figure opposite). When the **main contacts** separate, the current to be interrupted flows through a solenoid, thus creating an electromagnetic field B.

When the **arcing contacts** separate, the arc appears between them. The arc is made to rotate between the two circular arcing contacts by force F, the combined result of the electromagnetic field and the current.

Force F is directly proportional to the square of the current to be interrupted. **This breaking technique therefore automatically adapts to the current to be interrupted.** When the current is high, the speed of rotation is high (speed of sound) and cooling is intense. Just before reaching zero current, the speed is still sufficient to make the arc rotate and thus contribute to the recovery of dielectric strength at zero current. **Wear of the arcing contacts is very low.**

When the current is low, the speed of rotation is also low. **This leads to very soft breaking of the arc without surges,** comparable to the widely appreciated performances of the air breaking technique.



soft breaking

Breaking of inductive or capacitive currents.

The Rollarc contactor does not generate voltage surges.

On some switchgear such surges occur during the breaking of low inductive or capacitive currents and can damage the insulation of connected devices.

With the rotating arc technique, the rotation speed of the arc is low for low currents and breaking is soft under all conditions.

■ **current chopping:** (arc interruption before zero current) the chopping current is always less than 1A, i.e. the voltage surge is very low for the load.

■ **multiple prestrikes and restrikes**
Other phenomena exist that are much more dangerous to the load than the voltage surges resulting from current chopping. Such phenomena occur if the device tries to break high frequency currents.

High frequency currents appear when there is a dielectric breakdown (opening of contacts is too close to zero current) and produce high frequency waves that are very dangerous for motor insulation.

Given the relatively slow dielectric regeneration between its arcing contacts, the Rollarc contactor avoids breaking high

frequency currents and multiple prestrike and restrike phenomena are prevented.

The Rollarc is thus the perfect motor control contactor. It provides the user and the network with total security without requiring additional accessories such as surge arresters or RC systems.

Results of tests on Rollarc

motor starting current	busbar capacitance (Cb)	busbar capacitance and compensation (Cb+Cc)	overvoltage Pu (1)			multiple restrikes
			average	standard deviation	maxi	
100A	0.05 mF		1.76	0.18	2.35	none
100A		1.8 mF	1.88	0.13	2.23	none
300A	0.05 mF		1.69	0.10	1.90	none
300A		1.8 mF	1.79	0.09	1.91	none

(1) Pu = $\frac{\text{measured peak voltage}}{\frac{U\sqrt{2}}{\sqrt{3}}}$

$$(1) Pu = \frac{U\sqrt{2}}{\sqrt{3}}$$

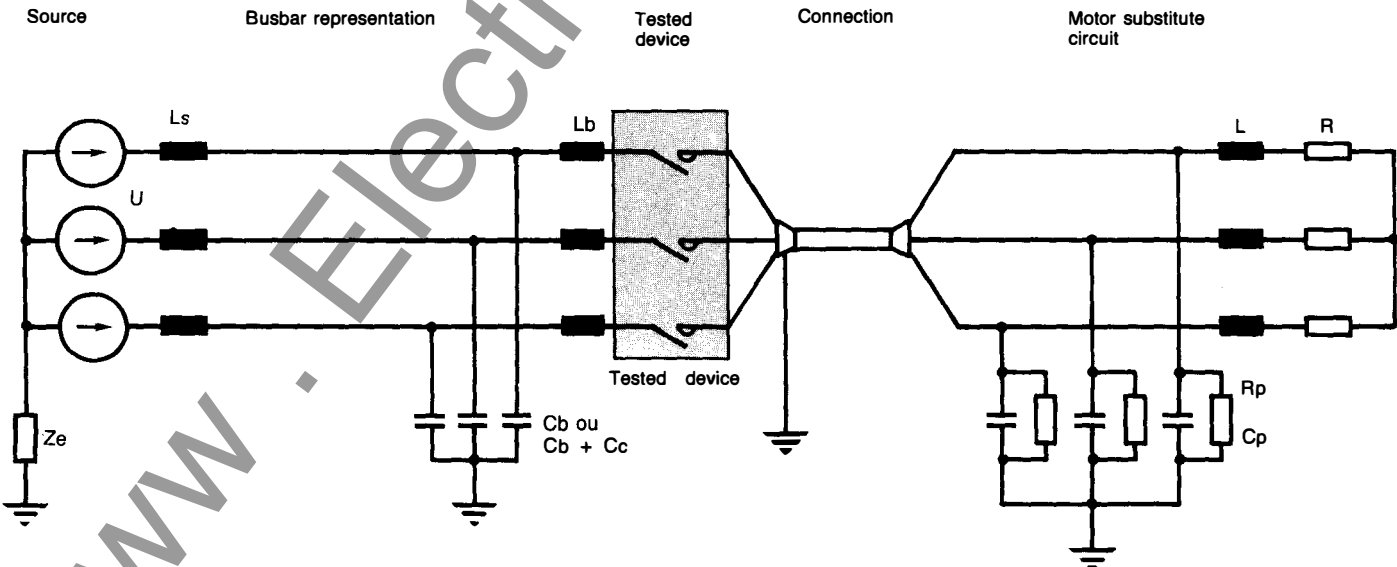
Example - peak voltage $7.2 \times 1.76 \frac{U\sqrt{2}}{\sqrt{3}} = 10.35 \text{ kV}$

■ tests according to IEC draft standard (17A secretariat 291)

Overvoltage levels depend on the breaking device, and also on the circuit. The IEC standard proposes a standard motor breaking circuit:

Test circuit diagram:

100A 7.2 kV and 300A 7.2 kV



- Z_e Earth impedance
- L_s Power supply inductance
- U Power supply voltage
- C_c Compensation capacitance
- C_b Capacitance of the bars
- L_b Inductance of the bars
- L Load inductance
- R Load resistance
- C_p Load parallel capacitance

Rollarc pole units

description

Each pole unit consists of:

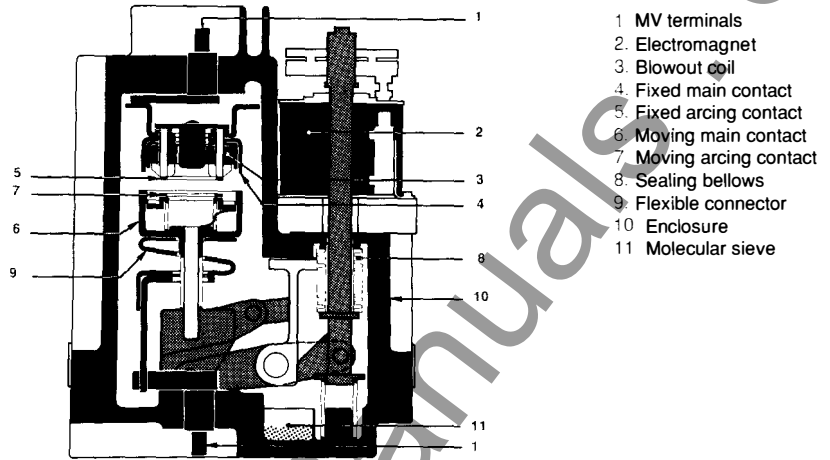
- a main circuit composed of a fixed main contact (4) and a moving main contact (6).

- a breaking circuit composed of a fixed arcing contact (5) and a moving arcing contact (7) that form two circular runners.

A blowout coil (3) is mounted in series in the circuit.

The main circuit that ensures the flow of the current is distinct from the breaking circuit in which the arc is produced.

- a transmission mechanism for the transfer of energy from the operating mechanism to the mobile contacts.



- 1 MV terminals
- 2 Electromagnet
- 3 Blowout coil
- 4 Fixed main contact
- 5 Fixed arcing contact
- 6 Moving main contact
- 7 Moving arcing contact
- 8 Sealing bellows
- 9 Flexible connector
- 10 Enclosure
- 11 Molecular sieve

operation

Rollarc 400 is a magnetic device that uses the rotating arc technique to interrupt the current.

- at the beginning of an opening cycle, the main contacts and the arcing contacts are closed (fig.1).

- isolation of the main circuit is achieved by the separation of the main contacts (fig. 2). The arcing contacts are still closed.

The current flows through the coil, the arcing contacts and the flexible connector.

- the arcing contacts open shortly after the main contacts. The resulting arc is made to rotate between the two circular runners of the arcing contacts by the electromagnetic field produced by the coil, the force of which depends on the current to be interrupted (fig. 3).

By design and due to phase shift between the current and the electromagnetic field, this force is still significant at zero current.

- at zero current, the gap between the contacts recovers its initial dielectric strength thanks to the inherent qualities of SF6 gas (fig. 4).

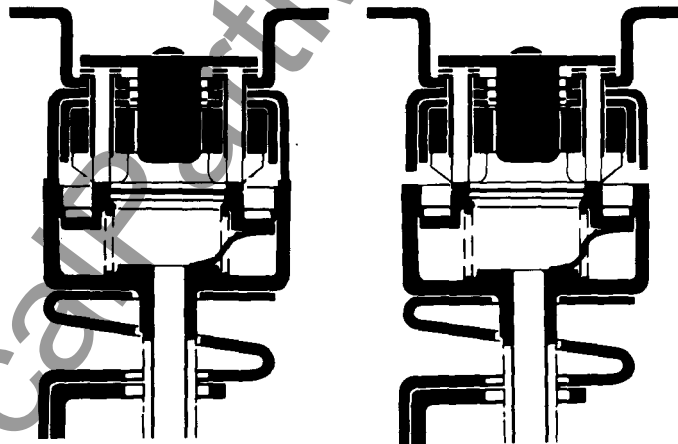


fig. 1

fig. 2

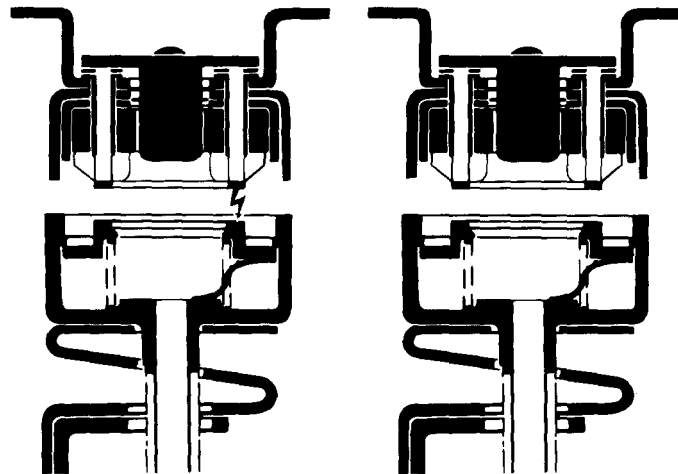


fig. 3

fig.4

fuse-contactor assembly utilisation guide

fuse-contactor combinations

Principle:

The **contactor** switches the load on and off during normal operation or an overload.

The **fuse** ensures correct interruption of short-circuit currents according to the network short-circuit level. A "fuse-blown" device causes contactor opening.

Economic advantages

For a short-circuit level of 500 MVA, or of 50 kA at 6 kV, the saving in switchgear costs is more than 50 % compared to a circuit breaker solution.

Technical advantages

Contactor: high switching rates and greater mechanical endurance than a circuit breaker.

Fuse: current limitation that considerably reduces the thermal and electrodynamic effects of a fault (fig. 1).

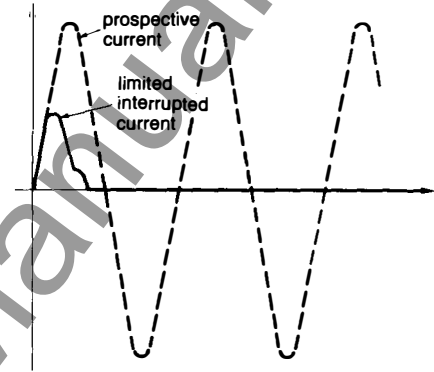


fig. 1 : prospective current and limited interrupted current.

fuse-contactor assembly transformer control and protection

Select the fuse using the table below.

Selection table (ratings in A) (1)

service voltage (kV)	type of fuse	transformer rating (kVA)														
		25	50	100	125	160	200	250	315	400	500	630	800	1000	1250	1600
3	Fusarc	16	25	40	50	50	63	80	80	100	125	160	200	250		
3.3		16	25	40	50	50	63	80	80	100	125	160	200	250		
4.16		10	25	31.5	40	50	50	63	80	80	100	125	160	200		
5.5		10	16	25	31.5	40	40	50	63	63	80	100	125	160	200	
6		10	16	25	31.5	31.5	40	50	50	63	80	80	100	125	160	200
6.6		10	16	25	25	31.5	40	40	50	63	80	80	100	125	160	200
10		6.3	10	16	25	25	31.5	31.5	40	50	50	63	80	80	100	
11		6.3	10	16	25	25	25	31.5	31.5	40	50	63	63	80	100	

(1) Installation without transformer overload

fuse-contactor assembly motor control

selection curves

The three sets of curves below enable the user to determine fuse ratings according to the motor power rating (P in kW) and its rated voltage (U in kV).

- set 1: provides the rated current in (A) using P and U.
- set 2: provides the starting current I_s (A) using I_n .
- set 3: provides the correct fuse rating according to I_s and the starting time t_s (s).

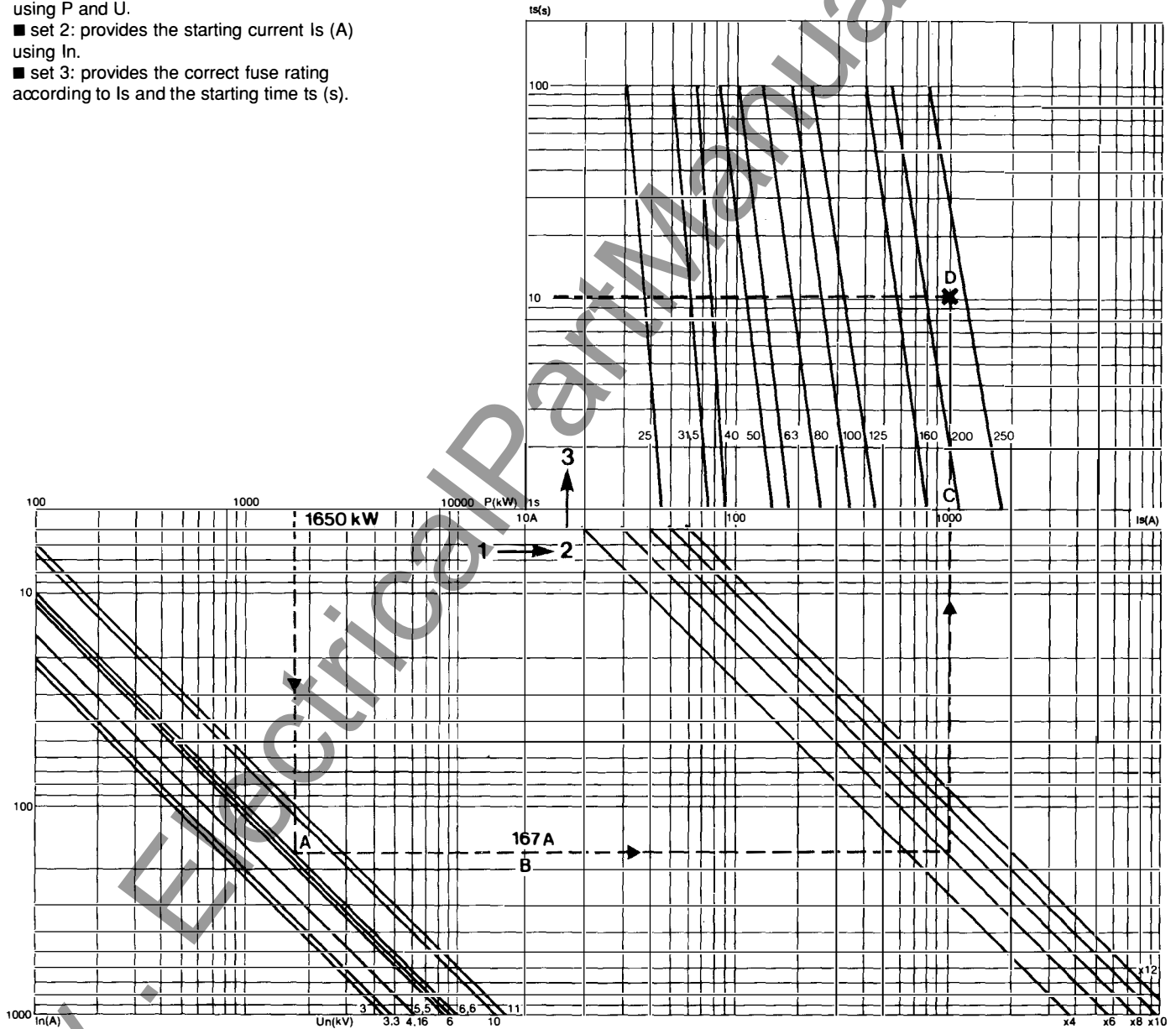
motor protection

The Fusarc fuse in association with a Rollarc contactor constitutes a particularly effective protection device for MV motors.

fuse ratings

Fuse ratings are determined according to three parameters depending on the motor characteristics:

- starting current I_s
- duration of start t_s
- switching rate



Example

- A 1650 kW motor supplied at 6.6 kV (point A) has a rated current I_n of 167 A (point B).
- the starting current is six times greater than the rated current, i.e. 1000 A (point C).
- for a ten second starting time t_s , the third set of curves indicates a rating of 250 A (point D).

Remarks:

- curve set 1 is plotted for a power factor (p.f.) of 0.92 and an output efficiency of 0.94. For different values, use the formula:

$$I_n = \frac{P}{\eta \sqrt{3} U_n \text{ p.f.}}$$

- the curves in set 3 are plotted for six starts spaced over one hour or two consecutive starts. For n starts spaced over one hour ($n > 6$), multiply t_s by $\frac{n}{6}$.

For p consecutive starts ($p > 2$), multiply t_s by $\frac{p}{2}$ (see selection table).

If the start duration information is not known, use $t_s = 10$ s.

- if motor start-up is not direct, the fuse rating obtained using the curves above may be insufficient for the full load current of the motor. A rating 20 % higher than the full load current should be selected to take into account installation in a cubicle.

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